

SKG093N规格书

L1+L5双频定位模块

SKG093N Datasheet

L1+L5 Dual-band Positioning Module

文档信息/Document information

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1 产品简介/Product Introduction

SKG093N 是一款高性能的面向车载导航领域的车载组合导航模块，模块能够同时支持 GPS、BDS、GLONASS、Galileo 以及 QZSS 的卫星定位系统、并且支持 L1+L5 双频定位。

SKG093N is a high-performance vehicle integrated navigation module for the field of vehicle navigation. The module can simultaneously support GPS, BDS, GLONASS, Galileo and QZSS satellite positioning systems, and support L1+L5 dual frequency positioning.



图 1: SKG093N 正视图/Top view

2 典型应用/Application

- ◆ 汽车导航/ Auto navigation
- ◆ 个人导航设备/ Personal navigation equipment
- ◆ 车辆远程监控/Remote vehicle monitoring

3 产品特点/Features

- ◆ L1 支持 GPS, GLO, GAL, BDS, QZSS 系统/ L1 supports GPS, GLO, GAL, BDS, QZSS systems
- ◆ L5 支持 GPS, GAL, BDS, QZSS/ L5 supports GPS, GAL, BDS, and QZSS
- ◆ 支持 SBAS(WAAS, EGNOS, MSAS, GAGAN)/ Support SBAS(WAAS, EGNOS, MSAS, GAGAN)
- ◆ 支持 RTCM(v2.3 和 v3.3) / Support RTCM(v2.3 和 v3.3)
- ◆ 标准通信协议 NEMA0183/Plug and play standard communication protocol NEMA0183
- ◆ 支持 AGPS: EPO, EASY, NVRAM, hotstill/ Support AGPS: EPO, EASY, NVRAM, hotstill
- ◆ 弱信号下具有较好的定位精度和位置有效性/ It has better positioning accuracy and location effectiveness under weak signals
- ◆ 符合 RoHS, FCC, CE /Compliance with RoHS, FCC, CE

5 传输及外设接口/Transmission and peripheral interface

5.1 PPS

秒脉冲 (PPS) : SKG093N 提供非常精准的时间脉冲 PPS 信号, PPS 信号可为外部系统提供授时功能, 脉冲宽度可调, 精度 20ns, 默认情况下每秒输出一个脉冲。

Second pulse (PPS): The SKG093N provides a very accurate time pulse PPS signal, the PPS signal can provide the timing function for the external system, the pulse width is adjustable, the accuracy is 20ns, by default, it output a pulse per second.

5.2 UART

SKG093N 模块提供了两个串口, 其中, UART0 用于发送卫星信息, UART2 用于输出差分信息。支持数据传输、固件升级功能, 输入/输出信号类型为 LVTTTL 电平(3.3V)。默认波特率为 115200bps, 最高可设为 921600bps, 串口波特率均可由用户自行配置。

The SKG093N module provides two serial ports. Serial UART0 is used to send satellite information, and serial port 2 is used to output differential information. Support data transmission, firmware upgrade function, input / output signal type is LVTTTL level(3.3V). The default port rate is 115200bps, which can be set up to 921600bps, and the serial port port rate can be configured by the user.

5.3 通信频率/Frequency of communication

目前, 系统支持输出 1hz 的数据刷新频率。

Currently, the system supports the output data refresh frequency of 1hz.

5.4 通信协议/Communication protocol

目前, SKG093N 模块输出常见的 NMEA0183 协议, 例如: GPGGA、GPRMC, GPGSV, GPGSA。At present, THE SKG093N module outputs common NMEA0183 protocols, such as GPGGA, GPRMC, GPGSV and GPGSA.

5.5 控制命令/Control command

SKG093N 系统支持用户通过串口发送控制命令, 但是, SKG093N 无法保存设置, 即 SKG093N 每次上电都是按默认方式输出。

The SKG093N system supports the user to send control commands through the serial port, but SKG093N cannot save the settings, that is, SKG093N is output by default every time it is powered on.

6 电气特性/Electrical specification

◆ 极限参数/limit Parameter

| 参数/Parameter | 符号/Symbol | 最小值/Min. | 最大值/Max. | 单位/Unit |
|--------------------------|-----------|----------|----------|---------|
| 电源/power supply | | | | |
| 供电电压/Supply Voltage | VCC | -0.3 | 3.6 | V |
| 输入输出/ IO | | | | |
| I/O 特性/I/O Features | VIO | -0.3 | 3.6 | V |
| RF 输入功率/RF Input power | RF_IN | | 0 | dBm |
| 静电保护/ESD | RF_IN | | 2000 | V |
| 环境/Environment | | | | |
| 存储温度/Storage temperature | Tstg | -40 | 85 | ° C |
| 湿度/Humidity | | | 95 | % |

◆ 电气特性/Electrical specification

| 参数/Parameter | 符号 /Symbol | 条件 /Condition | 最小值 /Min. | 典型值 /Type | 最大值 /Max. | 单位 /Unit |
|----------------------------|---------------|------------------|--------------|--------------|--------------|-------------|
| 电源电压/Supply voltage | VCC | | 3.0 | 3.3 | 3.6 | V |
| 电源电压/Supply voltage | V_BCKP | | 1.4 | 3.0 | 3.6 | V |
| 输入高压/input high voltage | VIH | | 2.4 | | 3.6 | V |
| 输入低压/input low voltage | VIL | | 0 | | 0.6 | V |
| 输出高压/output high voltage | VOH | Ioh=4mA | 2.8 | | | V |
| 输出低压/output low voltage | VOL | Iol=4mA | | | 0.4 | V |
| 工作温度/Operating temperature | Topr | | -40 | | 85 | °C |

7 性能指标/Performance evaluation

◆ 电气特性一倍标准差 (1 σ) GNSS 部分功能/Electrical characteristics one standard deviation (1 σ) GNSS partial function

| 参数/Parameter | 描述/Description | | |
|---|----------------------------------|--------------|---|
| 接收机类型/Receiver type | L1 | 1602 MHz | GLONASS L1OF |
| | | 1575.42 MHz | GPS L1CA QZSS L1CA SBAS L1 QZSS L1 SAIF Galileo E1 (E1B+E1C) |
| | | 1561.098 MHz | BeiDou B1I |
| | L5 | 1176.45 MHz | GPS L5 QZSS L5 Galileo E5a BeiDou B2a |
| 首次定位时间 TTFF | 冷启动/Cold Start≤28s | | |
| | 热启动/Hot Start≤1s | | |
| | 辅助启动/Auxiliary start≤5s | | |
| 灵敏度/Sensitivity | 跟踪/Tracking: -165dBm | | |
| | 捕获/Acquisition: -160dBm | | |
| | 冷启动/Cold Start: -148dBm | | |
| | 温启/Warm Start: -148dBm | | |
| | 热启动/Hot Start: -156dBm | | |
| 水平定位精度/Horizontal positioning precision | 自主定位/Autonomous positioning≤1.2m | | |
| | SBAS≤1m | | |
| PPS | 20ns | | |
| 速度精度/Speed precision | 0.05m/s | | |
| 功耗/ power dissipation | 50mA (3.3V) | | |
| 尺寸/Dimension | 10.1 x 9.7 x 2.2mm | | |
| 工作环境/Operational constraint | 动态/Dynamic≤4g | | |
| | 高度/Altitude≤50,000m | | |
| | 速度/Speed≤500m/s | | |

8 管脚定义/PIN Definition

| | | | | |
|---|------------|---------------------|-----------|----|
| 1 | GND | | GPIO2 | 18 |
| 2 | UART0_TX | | UART2_RXD | 17 |
| 3 | UART0_RX | | UART2_TXD | 16 |
| 4 | PPS | | VANT | 15 |
| 5 | WAKE_UP_IN | SKG093N Top view | VCC_RF | 14 |
| 6 | V_BACKP | | LNA_EN | 13 |
| 7 | NC | | GND | 12 |
| 8 | VCC | | RF_IN | 11 |
| 9 | RESET | | GND | 10 |

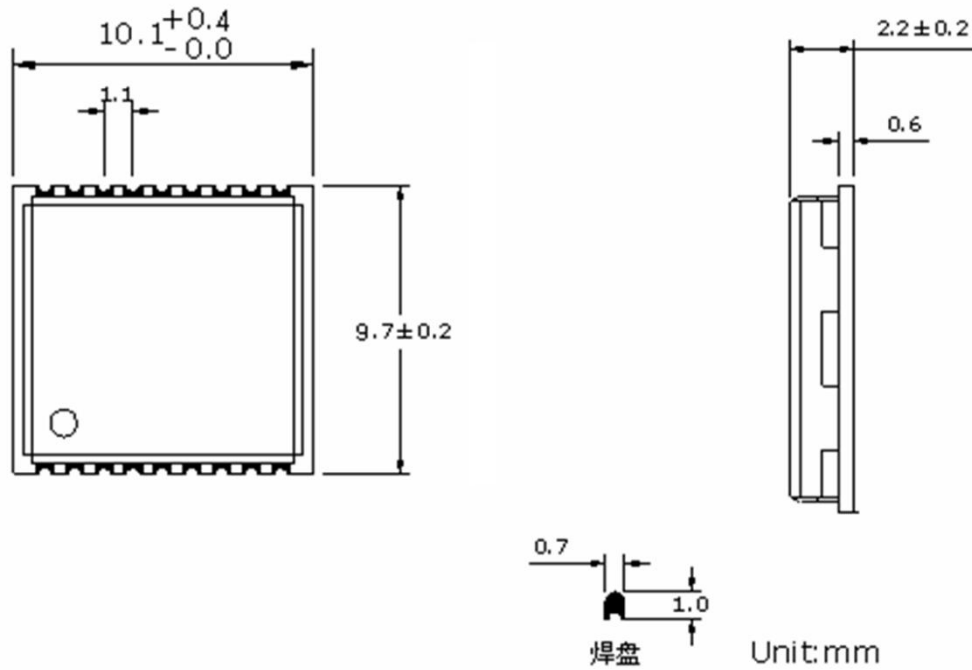
图 3: SKG093N 管脚定义/pin definitions

9 管脚描述/Pin description

| 管脚编号 /Pin No. | 管脚定义/Pin name | 使用说明/Description | 备注/Remark |
|------------------|------------------|---|-------------------------------------|
| 1 | GND | 电源地/GROUND | / |
| 2 | UART0_TX | UART0 串行数据输出/ UART serial data output | 默认数据输出脚/ Default data output pin |
| 3 | UART0_RX | UART0 串行数据输入/ UART serial data input | 默认数据输入脚/ Default data input pin |
| 4 | PPS | 秒脉冲信号输出/ Second pulse signal output | 不使用则悬空/ Leave open if not used |
| 5 | WAKE_UP_IN | 中断脚, 唤醒信号输入/ Interrupt pin, wake-up signal input | 不使用则悬空/ Leave open if not used |
| 6 | V_BCKP | 备份电源输入/ Backup power input | 不使用则悬空/ Leave open if not used |
| 7 | NC | / | / |
| 8 | VCC | 电源输入/ Power input | 不使用则悬空/ Leave open if not used |

| | | | |
|----|-----------|--|--|
| 9 | RESET | 复位信号输入/ Reset signal input | 不使用则悬空/ Leave open if not used |
| 10 | GND | 电源地/Ground | / |
| 11 | RF_IN | GNSS 天线接口 | 输入端须 50Ω阻抗匹配/ The input must match 50Ω impedance |
| 12 | GND | 电源地/Ground | / |
| 13 | LNA_EN | 2.8V 输出/ 2.8V output | 不使用则悬空/ Leave open if not used |
| 14 | VCC_RF | VCC 引脚电源输出/ VCC pin power output/ | 不使用则悬空/ Leave open if not used |
| 15 | VANT | 有源天线供电输入/ Active antenna power supply input | 不使用则悬空/ Leave open if not used |
| 16 | UART2_TXD | UART2 串行数据输出/ UART1 serial data output | 不使用则悬空/ Leave open if not used |
| 17 | UART2_RXD | UART2 串行数输入/ UART1 serial data Input | 不使用则悬空/ Leave open if not used |
| 18 | GPIO2 | 通用 I/O 口/General purpose I/O | 不使用则悬空/ Leave open if not used |

10 机械尺寸/Machine Dimension



| Parameter | specification | Units |
|-------------|---------------|-------|
| Coplanarity | ≤ 0.1 | mm |

图 4: SKG093N 机械尺寸/Machine Dimension

10.1 推荐封装/ Recommend Layout

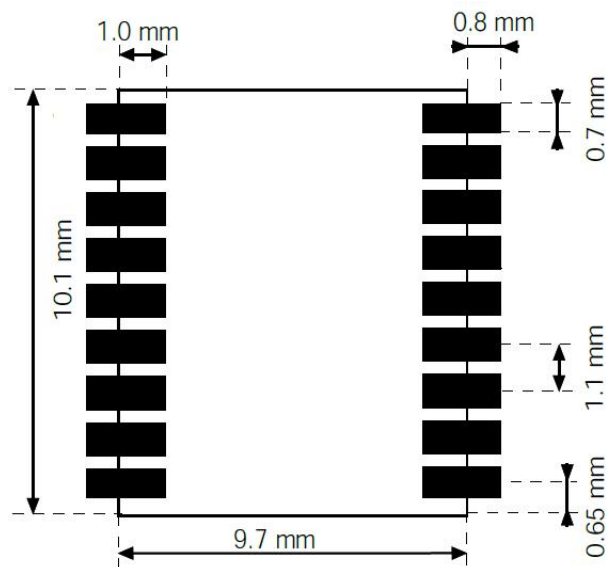


Figure 5: SKG093N Footprint

11 参考电路/Reference circuit

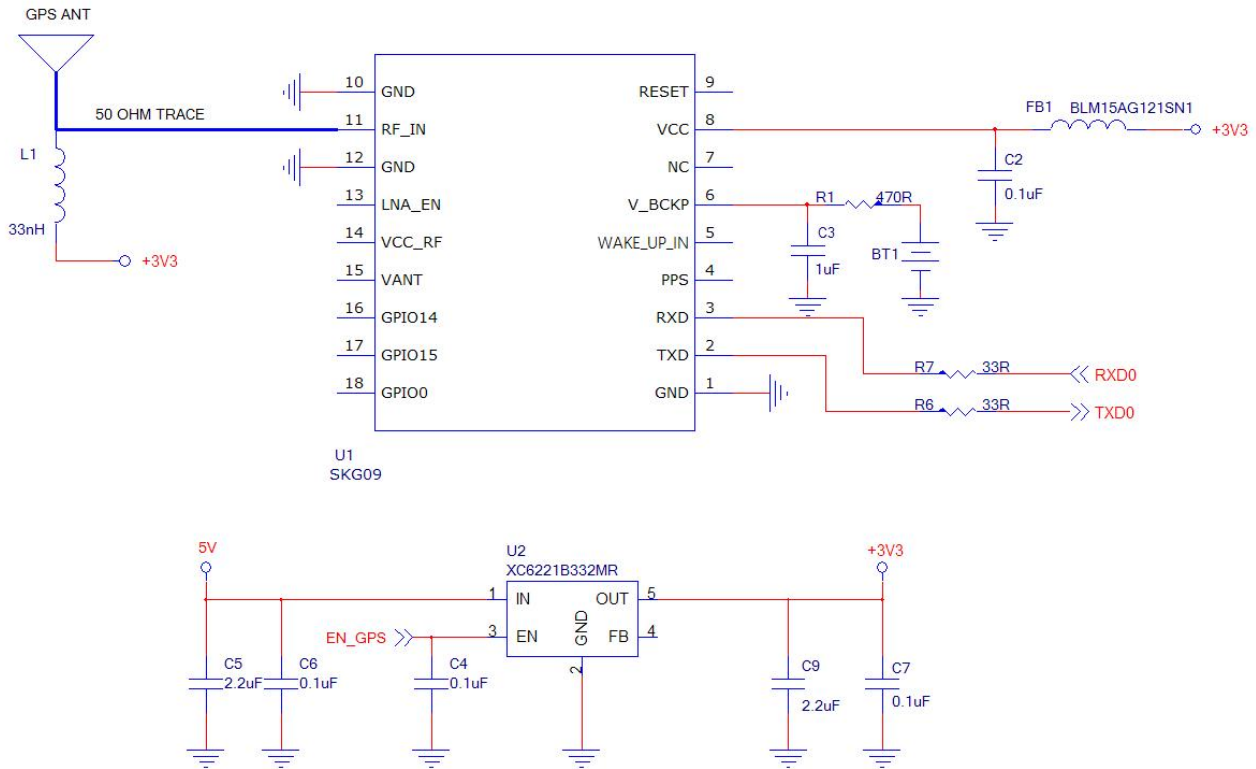


图 6: SKG093N 参考电路/Reference circuit

12 Layout 注意事项/ Layout Considerations

12.1 元件布局/ Placing Components

GNSS 模块在 PCB 上的布局对于获得最佳的 GNSS 性能来说是至关重要的。与天线的连接应越短越好，避免对信号造成过大的衰减。在系统板设计上，要确保射频电路跟其他数字电路严格分开，将模块远离 PCB 上的数字区域。同时还必须将 GNSS 模块远离发热量较大的区域。

The layout of GNSS modules on the PCB is critical for achieving optimal GNSS performance. The connection with the antenna should be as short as possible to avoid excessive attenuation of the signal. In the system board design, ensure that RF circuits are strictly separated from other digital circuits and that modules are kept away from the digital area on the PCB. At the same time, GNSS modules must be kept away from areas with high heat.

12.2 无源天线设计/ Passive Antenna Design

天线馈线的长度应尽可能短，且无源天线的下方要有一块完整的地。建议无源天线与 GNSS 模块放在 PCB 板相对的另一面。

The length of the antenna feeder should be as short as possible, and the passive antenna should have a complete ground below. It is recommended that the passive antenna and GNSS module be placed on the opposite side of the PCB board.

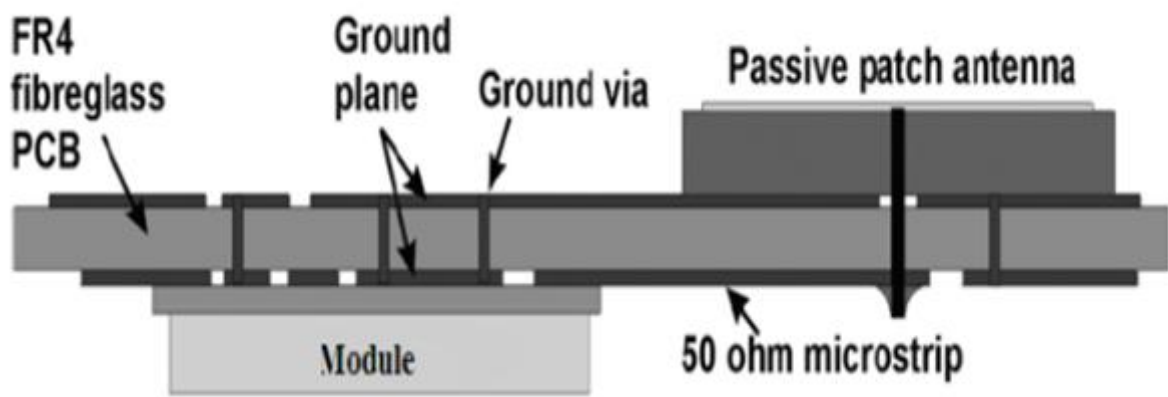


图 7：无源天线参考设计/ Passive Antenna eference design

12.3 阻抗匹配/ Impedance Matching

天线馈线的阻抗需为 50Ohm，为了达到 50 Ohm 的阻抗，微带线的宽度 W 要根据导线和参考面的距离 H ，PCB 介质板的介电常数 ϵ_r ，以及 PCB 的结构来选择。

The impedance of the antenna feeder shall be 50 Ohm. In order to achieve the impedance of 50 Ohm, the width W of the microstrip line shall be selected according to the distance H between the wire and the reference plane, the dielectric constant ϵ_r of the PCB dielectric board, and the structure of the PCB.

12.4 微带线设计/ Microstrip line design

微带线的长度应该尽可能的短，标准 PCB 上应该尽量不选用超过 2.5 cm (1 inch) 而又没有屏蔽层的微带线；

The length of microstrip lines should be as short as possible, and no microstrip lines exceeding 2.5cm (1 inch) without shielding layer should be selected on standard PCB as far as possible.

射频连接线的走线应避免靠近数字信号线；

Avoid routing RF cables close to digital signal cables.在连接地平面时要采用尽可能多的过孔；

在连接地平面时要采用尽可能多的过孔；

Wiring should be far away from noise sources, such as switching power supply, digital signal, crystal oscillator, processor, etc.

布线应远离噪声源，如:开关电源，数字信号，晶振，处理器等；

Wiring should be far away from noise sources, such as switching power supply, digital signal, crystal oscillator, processor, etc.

微带线相对应的参考地层应保持完整；

The reference strata corresponding to the microstrip line should be kept intact.

微带线特性阻抗必须为 50 ohm；

The characteristic impedance of microstrip line must be 50 ohm；

为了减小信号衰减，微带线走线时要避免锐角。

In order to reduce signal attenuation, the acute Angle should be avoided when microstrip lines are routed.

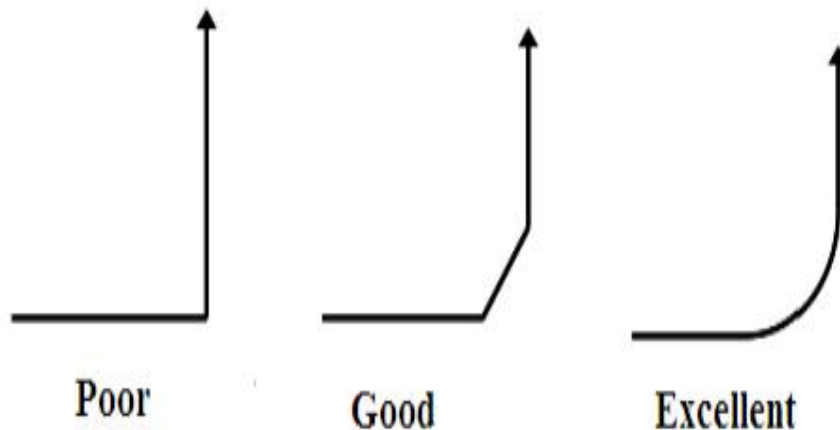


图 8：微带线设计推荐/ :microstrip cable design

13 软件说明/ Software description

13.1 NMEA 0183 协议/ The NMEA 0183 protocol is available

表 1-1 NMEA-0183 输出信息/ NMEA-0183 Output information

| NMEA 协议/NMEA protocol | 描述/Description | 默认/Default |
|-----------------------|----------------|------------|
|-----------------------|----------------|------------|

| | | |
|-----|---|------|
| GGA | 定位数据信息/ Global positioning system fixed data | 打开/Y |
| GSA | 当前卫星信息/ DOP and active satellites | 打开/Y |
| GSV | 可见卫星信息/ Satellites in view | 打开/Y |
| RMC | 推荐定位信息/Recommended minimum specific data | 打开/Y |
| GLL | 大地坐标信息/Geographic position—latitude/longitude | 打开/Y |
| VTG | 地面速度信息/ Course over ground and ground speed | 打开/Y |
| ZDA | 当前时间(UTC1)信息/Date and Time | 打开/Y |

表 1-2 标识符助记码/Identifier mnemonic code

| 标识符/Identifier | 数据类型/ Data type |
|----------------|--------------------------|
| GB | 北斗模式/ Beidou mode |
| GP | GPS 模式/ GPS mode |
| GN | GNSS 模式/ GNSS mode |
| GA | Galileo 模式/ Galileo mode |
| GL | GLONASS 模式/ GLONASS mode |

13.2 GGA-定位数据信息/GGA- Location information

此语句包含定位位置、定位时间、定位精度。

Contains the location, time, and precision factor of navigation positioning.

\$GNGGA,022326.000,2238.3443,N,11403.0962,E,1,22,0.72,104.0,M,-2.2,M,,*69

表 2-1 GGA 语句格式/GGA Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|---------------------------------|------------|----------|--------------------------------------|
| 语句 ID/Message ID | \$GNGGA | | 表明语句为 GGA 信息/ GGA protocol header |
| UTC 时间/UTC Position | 022326.000 | | hhmmss.sss 时分秒格式/Time seconds format |
| 纬度/ Latitude | 2238.3443 | | ddmm.mmmm 度分格式/Degree split format |
| 纬度 N/S / N/S indicator | N | | N=北纬 S=南纬/ N= north S= South |
| 经度/ Longitude | 11403.0962 | | dddmm.mmmm 度分格式/Degree split format |
| 经度 E/W / E/W Indicator | E | | E=东经 W=西经/ N=north or S=south |
| 定位状态/ Position Fix Indicator | 1 | | 见附表 2-2/ See Table 2-2 |
| 已使用卫星数量 /Satellites Used | 22 | | 范围 0 到 24/ Range 0 to 12 |

| | | | |
|--|-----------|-----|-----------------------------------|
| HDOP 水平精度因子 | 0.72 | | |
| 海拔高度/MSL Altitude | 104.0 | 米/M | |
| 单位/Unit | M | | |
| 大地水准面高度/ Geoidal height | -2.2 | | |
| 水准面划分单位/Level surface division unit | M | 米/M | |
| 校验值/Checksum | *69 | | |
| EOL | <CR> <LF> | | 结束标志符/ End of message termination |

表 2-2 定位状态描述/ Position Fix Indicators

| 数值/Value | 描述/Description |
|----------|--|
| 0 | 未定位或定位信息不可用/ Unpositioned or positioned information is not available |
| 1 | GNSS 定位/ GNSS fix |
| 2 | 差分 GNSS 定位(DGNSS, SBAS) / Differential GNSS fix(DGNSS, SBAS) |
| 3 | PPS 模式/ PPS model |

13.3 GSA-当前卫星信息/GSA- GNSS satellites in using

此条语句包含模块的选定工作模式，定位类型，已使用卫星的 PRN 信息及 PDOP, HDOP, VDOP 等信息。

This statement contains the selected working mode of the module, positioning type, PRN information of used satellites, PDOP, HDOP, VDOP and other information.

\$GNGSA,A,3,199,195,08,26,09,31,16,194,193,27,03,04,1.07,0.72,0.79,1*05

\$GNGSA,A,3,67,66,,,,,,,,,1.07,0.72,0.79,2*0E

\$GNGSA,A,3,,,,,,,,,1.07,0.72,0.79,3*0E

\$GNGSA,A,3,37,20,07,,,,,,,,,1.07,0.72,0.79,4*08

表 3-1 GSA 语句格式/GSA Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|--------------------------------------|------------|----------|--|
| 语句 ID/ Message ID | \$GNGSA | | 表明语句为 GSA 信息/ Indicates that the statement is GSA information |
| 模式 1/ Mode 1 | A | | 表 3-3/ See Table 3-3 |
| 模式 2/ Mode 2 | 3 | | 表 3-2/ See Table 3-2 |
| 已使用卫星 ID 信息/ ID of satellite used | 199 | | 第一信道的 Sv 信息/Sv on Channel 1 |
| 已使用卫星 ID 信息/ | 195 | | 第二信道的 Sv 信息/Sv on Channel 2 |

| | | | |
|--------------------------------------|-----------|--|--|
| ID of satellite used | | | |
| ... | ... | | ... |
| 已使用卫星 ID 信息/ ID of satellite used | <Null> | | 十二信道的 Sv 信息（未使用则为空）/ Sv on Channel 12 (Null fields when it is not Used) |
| PDOP | 1.07 | | 综合位置精度因子/Position Dilution of Precision |
| HDOP | 0.72 | | 水平精度因子/Horizontal Dilution of Precision |
| VDOP | 0.79 | | 垂直精度因子/Vertical Dilution of Precision |
| 校验值 | *05 | | |
| EOL | <CR> <LF> | | 结束标志符/End of message termination |

表 3-2/Table 3-2

| 值/Value | 描述/Description |
|---------|----------------|
| 1 | 未定位 |
| 2 | 2D 定位 |
| 3 | 3D 定位 |

表 3-3 /Table 3-3

| 值/Value | 描述/Description |
|---------|------------------|
| M | 手动选择 2D 或者 3D 模式 |
| A | 自动选择 2D 或者 3D 模式 |

13.4 GSV-可见卫星信息//GSV- GNSS Satellites in View

此语句包含可见卫星的 PRNs, 方位角和仰角等信息。

This sentence contains the mode of operation, type of fix, PRN of the satellites used in the solution as well as PDOP, HDOP and VDOP.

\$GPGSV,4,1,13,27,78,149,46,199,60,149,39,04,59,289,43,194,56,045,44,1*64

\$GPGSV,4,2,13,195,54,108,43,16,50,008,43,08,45,203,42,26,33,038,40,1*5A

\$GPGSV,4,3,13,09,28,313,33,31,28,098,42,193,26,167,39,03,11,233,39,1*52

\$GPGSV,4,4,13,22,,,35,1*60

\$GPGSV,3,1,10,27,78,149,50,199,60,149,48,04,59,289,46,194,56,045,45,8*6C

\$GPGSV,3,2,10,195,54,108,46,08,45,203,48,26,33,038,36,09,28,313,31,8*54

\$GPGSV,3,3,10,193,26,167,44,03,11,233,43,8*55

\$GLGSV,1,1,02,66,38,231,37,67,31,297,33,1*7A

\$GAGSV,1,1,02,05,,,41,24,,,41,7*72

\$GAGSV,1,1,02,05,,,45,24,,,41,1*70

\$GBGSV,3,1,11,07,65,346,40,37,50,357,43,23,33,068,26,10,32,262,41,1*7A

\$GBGSV,3,2,11,20,28,264,35,01,,,42,02,,,36,16,,,42,1*48

\$GBGSV,3,3,11,03,,,40,05,,,28,32,,,38,1*74

\$GBGSV,1,1,04,37,50,357,41,23,33,068,45,20,28,264,37,32,,,41,4*44

表 4-1 GSV 语句格式/ GSV Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|--------------------------------|------------|-----------|---|
| 语句 ID/Message ID | \$GPGSV | | 表明此语句为 GSV 信息/GSV protocol header |
| GSV 总数信息/ Number of Message | 4 | | 本次 GSV 语句的总条数/ Total number of GSV sentences |
| GSV 条数信息/ Message Number | 1 | | 本条语句为 GSV 语句中的第几条/ Sentence number of the total |
| 可见卫星信息/ Satellites in View | 13 | | 当前可见卫星总数/Number of satellites in view |
| 卫星 ID/Satellite ID | 27 | | |
| 卫星仰角/Elevation | 78 | 度/degrees | 范围 00 到 90/ Range 00 to 90 |
| 卫星方位角/Azinmuth | 149 | 度/degrees | 范围 000 到 359/ Range 000 to 359 |
| 信噪比(C/NO)/SNR(C/NO) | 46 | dB-Hz | 范围 00 到 90 (未使用则为空) / Range 00 to 99, null when not tracking |
| ... | | | ... |
| 可见卫星信息/ Satellites in View | 194 | | |
| 卫星 ID/Satellite ID | 56 | 度/degrees | 范围 00 到 90/ Range 00 to 90 |
| 卫星仰角/Elevation | 045 | 度/degrees | 范围 000 到 359/ Range 000 to 359 |
| 卫星方位角/Azinmuth | 44 | dB-Hz | 范围 00 到 90 (未使用则为空) / Range 00 to 99, null when not tracking |
| 校验值/Checksum | *64 | | |
| EOL | <CR> <LF> | | 结束标志符/End of message termination |

13.5 RMC-推荐定位信息/ RMC- Recommended locating information

此语句包含推荐定位的卫星定位信息。

This statement contains the satellite positioning information for the recommended location.

\$GNRMC,022326.000,A,2238.3443,N,11403.0962,E,0.01,169.33,120421,,A,V*07

表 5-1: RMC 语句格式/ RMC Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|------------------------------------|------------|----------|--|
| 语句 ID/Message ID | \$GNRMC | | 表明此语句为 RMC 信息/RMC protocol header |
| UTC 时间/UTS Position | 022326.000 | | hhmmss.sss |
| 使用状态/Status | A | | A=数据已使用 V=数据未使用/A=data valid or V=data not valid |
| 纬度/ Latitude | 2238.3443 | | ddmm.mmmm |
| 纬度 N/S/ N/S Indicator | N | | N=北纬 S=南纬/N=north or S=south |
| 经度/Longitude | 11403.0962 | | dddmm.mmmm |
| 经度 E/W /E/W Indicator | E | | E=东经 W=西经/E=east or W=west |
| 速度/ Speed Over Ground | 0.01 | 节 | |
| 方位角/Course Over Ground | 169.33 | 度 | |
| UTC 日期/Date(UTC) | 120421 | | ddmmyy |
| 磁偏角/Magnetic variation | <Null> | 度 | 未使用则为空/Null fields when it is not Used |
| 磁偏角方位/Magnetic Variation Direction | <Null> | | E=东经 W=西经 /E=east or W=west |
| 定位模式/Fix Mode | A | | A=自动, N=未定位, D=DGPS, E=DR/ A=autonomous, N = No fix, D=DGPS, E=DR |
| 校验值/Checksum | *07 | | |
| EOL | <CR> <LF> | | 结束标志符/End of message termination |

13.6 GLL-地理定位信息/Geographic Position – Latitude/Longitude

包含纬度和经度信息。

This sentence contains the fix latitude and longitude.

\$GNGLL, 2238.3443,N, 11403.0962,E, 022326.000,A,A*4F

表 6-1: GLL 数据格式/GLL Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|----------------------|------------|----------|--|
| 语句/ Message ID | \$GNGLL | | GLL protocol header |
| 纬度/ Latitude | 2238.3443 | | ddmm.mmmm |
| 南北纬度/N/S Indicator | N | | N=north or S=south |
| 经度/ Longitude | 11403.0962 | | dddmm.mmmm |
| 东西经度/ E/W Indicator | E | | E=east or W=west |
| UTC 定位/ UTC Position | 022326.000 | | hhmmss.sss |
| Fix 状态/Fix Status | A | | A=data valid or V=data not valid |
| Fix 模式/Fix Mode | A | | A=autonomous, N = No fix, D=DGPS, E=DR |
| 校验和/ Checksum | *4F | | |
| EOL | <CR> <LF> | | 信息结束标志符/End of message |

13.7 VTG-地面速度信息/VTG- Course Over Ground and Ground Speed

此语句包含地面速度信息。

This statement contains the ground speed information.

\$GNVTG,169.33,T,,M,0.01,N,0.02,K,A*2E

表 7-1: VTG 语句格式/VTG statement format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|---|------------|----------|---|
| 语句 ID/Message ID | \$GNVTG | | 表明此语句为 VTG 信息/VTG protocol header |
| 以真北为参考的地面航向 /Ground course with true north as reference | 169.33 | | 000~359 度，前面的 0 也将被传输/At 000~359 degrees, the front 0 will also be transmitted |
| 间隔符/Blank character | T | | |

| | | | |
|---|-----------|--------|---|
| 以磁北为参考的地面航向 /Ground heading with magnetic north as reference | <Null> | | 000~359 度, 前面的 0 也将被传输/At 000~359 degrees, the front 0 will also be transmitted |
| 间隔符/Blank character | M | | |
| 地面速率/Ground rate | 0.01 | Knots | 000.0~999.9 |
| 间隔符 /Blank character | N | | |
| 地面速率/Ground rate | 0.02 | Km / h | 0000.0~1851.8Km / h |
| 间隔符 /Blank character | K | | |
| 模式指示/Mode indication | A | | A=自主定位, D=差分, E=估算, N=数据无效/ A= autonomous localization, D= difference, E= imputation, and N= invalid data |
| EOL | <CR> <LF> | | 结束标志符/ End of message termination |

13.8 ZDA-时间日期信息/ ZDA- Date and Time

此语句包含时间和日期信息

This sentence contains UTC date & time, and local time zone offset information.

\$GNZDA,022326.000,12,04,2021,,*49

表 8-1: ZDA 语句格式/ ZDA Data Format

| 名称/Name | 举例/Example | 单位/Units | 描述/Description |
|---------------------|------------|----------|-----------------------------------|
| 语句 ID/Message ID | \$GNZDA | | 表明此语句为 ZDA 信息/ZDA protocol header |
| UTC 时间/UTC Time | 022326.000 | | hhmmss (时分秒) 格式 |
| UTC 日期/UTC data | 12 | | 日 |
| UTC 日期/UTC Month | 04 | | 月 |
| UTC 日期/UTC Year | 2021 | | 年 |
| 时区/local zone hours | <Null> | | |
| 校验值/Checksum | *49 | | |
| EOL | <CR> <LF> | | 结束标志符/ End of message termination |

14 联系方式/ Contact Information

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